

On maxentropic reconstruction of multiple Markov chains

by

COSTEL BĂLCĂU AND VASILE PREDA

Abstract

We use the maxentropic reconstruction method for obtaining some homogeneous and stationary multiple Markov chains.

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1 Introduction

The problems of reconstruction of a countable probability distribution or of a homogeneous and stationary simple or multiple Markov chain with discrete time and countable state space, when only a partial information is known, present a remarkable interest in many applications from various sciences (see Fang, Rajasekera and Tsao [2], Guiaşu [3], Iosifescu [7], Iosifescu and Grigorescu [8], for example). Jaynes [10, 11] and Kullback [12] proposed a variational method for solving such problems, called the *method of standard maximum entropy (SME)*. This method states that one should choose the probability distribution that maximizes the Shannon entropy [16]. In the case of multiple Markov chains, we can use the Iosifescu-Theodorescu entropy [9] (see Preda and Bălcău [14]).

In this article we recast the proposed problem as a linear inverse problem and we solve it by using the *method of maximum entropy in the mean (MEM)*. This method, originally proposed by Rietch [15], was used by Gzyl [4] for finite probability distributions, Gzyl and Velásquez [6] for homogeneous simple Markov chains with finite state space, Preda and Bălcău [13] for countable simple Markov chains with common steady-state probabilities and for matrix scaling problems.

In Section 2 we present the general frame of the MEM method and we apply this method for maxentropic reconstruction of some nonnegative multidimensional matrices. In Section 3 we derive a method to obtain countable multiple Markov chains with fixed joint probabilities. We give an example for our approach.

2 MEM method

We consider the following linear inverse problem

$$\begin{aligned} Ax &= b, \\ x &\in \mathcal{C}, \end{aligned} \quad (1)$$

where

$$\mathcal{C} = \left\{ x = (x_i)_{i \in I} / x_i \geq 0, \forall i \in I, \sum_{i \in I} x_i < \infty \right\}, \quad (2)$$

$A : \mathcal{C} \rightarrow \mathbb{R}^K$ is a bounded linear operator, $b \in \mathbb{R}^K$, I and K being two countable (finite or infinite) sets of indices.

Let $(\Omega, \mathcal{B}, \nu)$ be a probability space, and let $X : (\Omega, \mathcal{B}) \rightarrow (\mathcal{C}, \mathcal{B}(\mathcal{C}))$ be a random variable. Usually, $\Omega = \mathcal{C}$ and we suppose that

$$\overline{\text{co}}(\text{supp } \nu) = \mathcal{C},$$

where $\text{supp } \nu$ is the support of ν and $\overline{\text{co}}(\text{supp } \nu)$ is the closed convex hull generated by $\text{supp } \nu$.

If the set K is infinite, then we suppose also that

$$\Omega \text{ is countable, } b \text{ is bounded, } A \geq 0 \text{ and } b \geq 0. \quad (3)$$

Definition 2.1. Let $\mathcal{M}_0$ be the set of all probability measures on $(\Omega, \mathcal{B})$, and let

$$\mathcal{M}(\nu, A, b) = \{\mu \in \mathcal{M}_0 / \mu \prec \nu, AE_\mu[X] = b\}.$$

For all $\mu \in \mathcal{M}(\nu, A, b)$, let

$$H(\mu; \nu) = \begin{cases} \int_{\Omega} \frac{d\mu}{d\nu} \ln \frac{d\mu}{d\nu} d\nu, & \text{if } E_\mu \left[\left| \ln \frac{d\mu}{d\nu} \right| \right] < \infty, \\ +\infty, & \text{otherwise} \end{cases}$$

(the relative entropy of μ with respect to ν ; the cross-entropy of ν with respect to μ ; the Kullback-Leibler number).

We consider the following entropy optimization problem, according to SME method:

$$\text{Program (P1)} : \begin{cases} \max -H(\mu; \nu) & \text{s.t.} \\ \mu \in \mathcal{M}(\nu, A, b). \end{cases}$$

MEM method is based on the following result (see [5] or [1], Theorem 1):

Theorem 2.1. If μ is a feasible solution for program (P1), then $x = E_\mu[X]$ is a solution of linear inverse problem (1).

Next, we derive a convex dual program of program (P1).

Definition 2.2. For all $\lambda \in \mathbb{R}^K$, let the measure $\mu(\lambda)$ defined by

$$d\mu(\lambda) = \frac{e^{-\langle \lambda, AX \rangle}}{Z(\lambda)} d\nu, \text{ where } Z(\lambda) = \int_{\Omega} e^{-\langle \lambda, AX \rangle} d\nu.$$

Definition 2.3. Let the set

$$\Lambda(\nu, A, b) = \begin{cases} \{\lambda \in \mathbb{R}^K / Z(\lambda) < \infty\}, & \text{if } K \text{ is finite,} \\ \{\lambda \in \mathbb{R}_+^K / Z(\lambda) < \infty, \sum_{k \in K} \lambda_k < \infty\}, & \text{if } K \text{ is infinite,} \end{cases}$$

and let the function $L : \Lambda(\nu, A, b) \rightarrow \mathbb{R}$ defined by

$$L(\lambda) = \ln Z(\lambda) + \langle \lambda, b \rangle, \quad \forall \lambda \in \Lambda(\nu, A, b).$$

Remark 2.1. For all $\lambda \in \Lambda(\nu, A, b)$, $\mu(\lambda)$ is a probability measure on $(\Omega, \mathcal{B})$ (i.e. $\mu(\lambda) \in \mathcal{M}_0$) and $\mu(\lambda) \prec \nu$.

We can define the following geometric dual problem for program (P1):

$$\text{Program (D1)} : \begin{cases} \min L(\lambda) & \text{s.t.} \\ \lambda \in \Lambda(\nu, A, b). \end{cases}$$

We have the following duality theorem (see [13], Theorems 1 and 2):

Theorem 2.2. (i) **(weak duality)** If μ is a primal feasible solution of program (P1) and λ is a dual feasible solution of program (D1), then

$$-H(\mu; \nu) \leq L(\lambda).$$

Moreover, the equality holds if and only if

$$d\mu = \frac{e^{-\langle \lambda, AX \rangle}}{Z(\lambda)} d\nu.$$

(ii) **(strong duality)** Assume that

$$\int_{\Omega} e^{s\|X\|} d\nu < \infty, \quad \forall s \in \mathbb{R}. \quad (4)$$

If $\lambda^* \in \text{Int } \Lambda(\nu, A, b)$ is a dual optimal solution of program (D1), then $\mu(\lambda^*)$ is a primal optimal solution of program (P1) and the duality gap vanishes, i.e.

$$-H(\mu(\lambda^*); \nu) = L(\lambda^*).$$

Remark 2.2. The assumptions (3), $\lambda \geq 0$, $\sum_{k \in K} \lambda_k < \infty$ and (4) are imposed for proving the theorem in the countable infinite case (see [13]).

Next we apply the MEM method to obtain d -dimensional matrices

$$T = (T_{i_1, \dots, i_d})_{i_1, \dots, i_d \in J}$$

verifying the constraints similar to (1). Particularly, in Section 3 we apply the procedure to obtain countable Markov chains of order r with fixed joint probabilities of the states at r consecutive times and with r -step transition probabilities verifying some given linear constraints.

Let $d \in \mathbb{N}^*$, J be a countable (finite or infinite) set of indices, and let

$$I = J^d, \Omega = \prod_{(i_1, \dots, i_d) \in I} \Omega_{i_1, \dots, i_d},$$

$$\mathcal{B} = \bigotimes_{(i_1, \dots, i_d) \in I} \mathcal{B}(\Omega_{i_1, \dots, i_d}), \nu = \bigotimes_{(i_1, \dots, i_d) \in I} \nu_{i_1, \dots, i_d},$$

where, for all $(i_1, \dots, i_d) \in I$, $(\Omega_{i_1, \dots, i_d}, \mathcal{B}(\Omega_{i_1, \dots, i_d}), \nu_{i_1, \dots, i_d})$ is a probability space.

Taking $\mu = \bigotimes_{(i_1, \dots, i_d) \in I} \mu_{i_1, \dots, i_d}$, where, for all $(i_1, \dots, i_d) \in I$, $\mu_{i_1, \dots, i_d}$ is a probability measure on the space $(\Omega_{i_1, \dots, i_d}, \mathcal{B}(\Omega_{i_1, \dots, i_d}))$, the primal problem (P1) has now the following form:

$$\text{Program (P2) : } \begin{cases} \max -H(\mu; \nu) & \text{s.t.} \\ \mu_{i_1, \dots, i_d} \prec \nu_{i_1, \dots, i_d}, \forall (i_1, \dots, i_d) \in I, \\ \sum_{(i_1, \dots, i_d) \in I} A_{i_1, \dots, i_d}^{(k)} E_{\mu_{i_1, \dots, i_d}}[X_{i_1, \dots, i_d}] = b_k, \forall k \in K. \end{cases}$$

According to the above assumptions, K is a countable set of indices, $X = (X_{i_1, \dots, i_d})_{(i_1, \dots, i_d) \in I}$ is a random variable on $(\Omega, \mathcal{B})$ with values in the space $(\mathcal{C}, \mathcal{B}(\mathcal{C}))$ defined by

$$\mathcal{C} = \left\{ x = (x_{i_1, \dots, i_d})_{(i_1, \dots, i_d) \in I} / x \geq 0, \sum_{(i_1, \dots, i_d) \in I} x_{i_1, \dots, i_d} < \infty \right\},$$

$A : \mathcal{C} \rightarrow \mathbb{R}^K$ is a bounded linear operator, $b \in \mathbb{R}^K$, and the conditions (3) are also satisfied.

The maxentropic reconstruction of some d -dimensional matrices

$$T = (T_{i_1, \dots, i_d})_{i_1, \dots, i_d \in J}$$

that verify the following linear system

$$\begin{aligned} AT &= b, \\ T &\in \mathcal{C}, \end{aligned} \tag{5}$$

is based on the following direct consequence of Theorem 2.1.

Corollary 2.1. *If μ is a feasible solution for program (P2), then the matrix $T = (T_{i_1, \dots, i_d})_{(i_1, \dots, i_d) \in I}$ given by*

$$T_{i_1, \dots, i_d} = E_{\mu_{i_1, \dots, i_d}}[X_{i_1, \dots, i_d}], \forall (i_1, \dots, i_d) \in I$$

is a d -dimensional matrix which verifies (5).

Next, we derive a geometric dual program of program (P2). We have

$$Z(\lambda) = \int_{\Omega} e^{-\langle \lambda, \mathbf{A} \mathbf{X} \rangle} d\nu = \prod_{(i_1, \dots, i_d) \in I} \zeta_{i_1, \dots, i_d}((\mathbf{A}^* \lambda)_{i_1, \dots, i_d}),$$

where

$$\zeta_{i_1, \dots, i_d}(y) = \int_{\Omega_{i_1, \dots, i_d}} e^{-y x_{i_1, \dots, i_d}} d\nu_{i_1, \dots, i_d}(x_{i_1, \dots, i_d}).$$

The dual problem for program (P2) has the following form:

$$\text{Program (D2)} : \begin{cases} \min L(\lambda) = \sum_{(i_1, \dots, i_d) \in I} \ln \zeta_{i_1, \dots, i_d}((\mathbf{A}^* \lambda)_{i_1, \dots, i_d}) + \langle \lambda, \mathbf{b} \rangle & \text{s.t.} \\ \lambda \in \Lambda(\nu, \mathbf{A}, \mathbf{b}), \end{cases}$$

where $\Lambda(\nu, \mathbf{A}, \mathbf{b})$ is given by Definition 2.3.

As a direct consequence of Theorem 2.2, we have the next duality result.

Corollary 2.2. *ssume that $\sum_{(i_1, \dots, i_d) \in I} \int_{\Omega_{i_1, \dots, i_d}} X_{i_1, \dots, i_d} d\nu_{i_1, \dots, i_d} < \infty$.*

(i) **(weak duality)** *If μ is a primal feasible solution of program (P2) and λ is a dual feasible solution of program (D2), then*

$$-H(\mu; \nu) \leq L(\lambda).$$

Moreover, the equality holds if and only if

$$d\mu_{i_1, \dots, i_d} = \frac{e^{-(\mathbf{A}^* \lambda)_{i_1, \dots, i_d} X_{i_1, \dots, i_d}}}{\zeta_{i_1, \dots, i_d}((\mathbf{A}^* \lambda)_{i_1, \dots, i_d})} d\nu_{i_1, \dots, i_d}, \quad \forall (i_1, \dots, i_d) \in I.$$

(ii) **(strong duality)** *If $\lambda^* \in \text{Int } \Lambda(\nu, \mathbf{A}, \mathbf{b})$ is a dual optimal solution of program (D2), then $\mu(\lambda^*) = \bigotimes_{(i_1, \dots, i_d) \in I} \mu_{i_1, \dots, i_d}(\lambda^*)$ given by*

$$d\mu_{i_1, \dots, i_d}(\lambda^*) = \frac{e^{-(\mathbf{A}^* \lambda^*)_{i_1, \dots, i_d} X_{i_1, \dots, i_d}}}{\zeta_{i_1, \dots, i_d}((\mathbf{A}^* \lambda^*)_{i_1, \dots, i_d})} d\nu_{i_1, \dots, i_d}, \quad \forall (i_1, \dots, i_d) \in I$$

is a primal optimal solution of program (P2) and the duality gap vanishes, i.e.

$$-H(\mu(\lambda^*); \nu) = L(\lambda^*).$$

3 Reconstruction of some countable multiple Markov chains

In this section we apply the above results to obtain homogeneous and stationary Markov chains of order r ($r \in \mathbb{N}^*$) $\{X(t) / t \in \mathbb{N}\}$ with the countable (finite or infinite) state space J and with r -step transition probability array $\mathbf{P}^{(r)} =$

$\left(P_{i_1, \dots, i_r; j}^{(r)}\right)_{i_1, \dots, i_r, j \in J}$ verifying the constraints (5) for $d = r + 1$. We recall that for any $j, i_1, \dots, i_r \in I$

$$P_{i_1, \dots, i_r; j}^{(r)} = P(X(t+r) = j / X(t) = i_1, \dots, X(t+r-1) = i_r), \forall t \in \mathbb{N}.$$

Particularly, we obtain homogeneous and stationary Markov chains of order r without supplementary constraints, i.e. the r -step transition probability array verifying only the imposed constraints

$$\left\{ \begin{array}{l} \sum_{j \in J} P_{i_1, \dots, i_r; j}^{(r)} \geq 0, \forall j, i_1, \dots, i_r \in J, \\ \sum_{j \in J} P_{i_1, \dots, i_r; j}^{(r)} = 1, \forall i_1, \dots, i_r \in J, \\ \sum_{i_1, \dots, i_r \in J} \pi_{i_1, \dots, i_r}^{(r)} P_{i_1, \dots, i_r; j}^{(r)} = \sum_{i_1, \dots, i_{r-1} \in J} \pi_{i_1, \dots, i_{r-1}, j}^{(r)}, \forall j \in J, \end{array} \right. \quad (6)$$

where $\pi^{(r)} = \left(\pi_{i_1, \dots, i_r}^{(r)}\right)_{i_1, \dots, i_r \in J}$ is the given joint probability of the states at r consecutive times, i.e. for any $i_1, \dots, i_r \in I$

$$\pi_{i_1, \dots, i_r}^{(r)} = P(X(t) = i_1, \dots, X(t+r-1) = i_r), \forall t \in \mathbb{N}.$$

Remark 3.1. Obviously, the chain $\{X(t) / t \in \mathbb{N}\}$ is completely characterized by the distribution $\pi^{(r)}$ and the transition probability array $P^{(r)}$ verifying the constraints (6) and the following constraints

$$\pi_{i_1, \dots, i_r}^{(r)} > 0, \forall i_1, \dots, i_r \in I, \quad (7)$$

$$\sum_{i_1, \dots, i_r \in I} \pi_{i_1, \dots, i_r}^{(r)} = 1, \quad (8)$$

$$\sum_{i_1, \dots, i_k \in I} \pi_{i_1, \dots, i_k, i_{k+1}, \dots, i_r}^{(r)} = \sum_{i_1, \dots, i_k \in I} \pi_{i_{k+1}, \dots, i_r, i_1, \dots, i_k}^{(r)}, \forall 1 \leq k \leq r-1. \quad (9)$$

In this particular case $P^{(r)}$ is a solution of (5) by taking

$$\begin{aligned} d &= r + 1, \\ K &= J^r \cup (-J), \\ A_{i_1, \dots, i_r, j}^{(k_1, \dots, k_r)} &= \begin{cases} 1, & \text{if } (i_1, \dots, i_r) = (k_1, \dots, k_r), \\ 0, & \text{if } (i_1, \dots, i_r) \neq (k_1, \dots, k_r), \end{cases} \quad \forall i_1, \dots, i_r, j, k_1, \dots, k_r \in J, \\ A_{i_1, \dots, i_r, j}^{(-k)} &= \begin{cases} \pi_{i_1, \dots, i_r}^{(r)}, & \text{if } j = k, \\ 0, & \text{if } j \neq k, \end{cases} \quad \forall i_1, \dots, i_r, j, k \in J, \\ b_{k_1, \dots, k_r} &= 1, \quad \forall k_1, \dots, k_r \in J, \\ b_{-k} &= \pi_k, \quad \forall k \in J, \end{aligned}$$

where

$$\pi_k = \sum_{i_1, \dots, i_{r-1} \in J} \pi_{i_1, \dots, i_{r-1}, k}^{(r)}, \quad \forall k \in J.$$

The primal problem (P2) has now the following form:

$$\text{Program (P3)} : \left\{ \begin{array}{l} \max -H(\mu; \nu) \quad \text{s.t.} \\ \mu_{i_1, \dots, i_r, j} \prec \nu_{i_1, \dots, i_r, j}, \quad \forall i_1, \dots, i_r, j \in J, \\ \sum_{j \in J} E_{\mu_{i_1, \dots, i_r, j}} [X_{i_1, \dots, i_r, j}] = 1, \quad \forall i_1, \dots, i_r \in J, \\ \sum_{i_1, \dots, i_r \in J} \pi_{i_1, \dots, i_r}^{(r)} E_{\mu_{i_1, \dots, i_r, j}} [X_{i_1, \dots, i_r, j}] = \pi_j, \quad \forall j \in J. \end{array} \right.$$

The maxentropic reconstruction of r -step transition probability array $P^{(r)} = (P_{i_1, \dots, i_r, j}^{(r)})_{i_1, \dots, i_r, j \in J}$ is based on the following direct consequence of Corollary 2.1.

Corollary 3.1. *If μ is a feasible solution of (P3), then the matrix $P^{(r)} = (P_{i_1, \dots, i_r, j}^{(r)})_{i_1, \dots, i_r, j \in J}$ given by*

$$P_{i_1, \dots, i_r, j}^{(r)} = E_{\mu_{i_1, \dots, i_r, j}} [X_{i_1, \dots, i_r, j}], \quad \forall i_1, \dots, i_r, j \in J$$

is a solution for system (6).

Obviously, we have

$$\begin{aligned} \langle \lambda, b \rangle &= \sum_{k_1, \dots, k_r \in J} \lambda_{k_1, \dots, k_r} + \sum_{k \in J} \pi_k \lambda_{-k}, \\ (A^* \lambda)_{i_1, \dots, i_r, j} &= \lambda_{i_1, \dots, i_r} + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j}, \quad \forall i_1, \dots, i_r, j \in J, \end{aligned}$$

and hence we obtain that the geometric dual problem of (P3) has the following form:

$$\text{Program (D3)} : \left\{ \begin{array}{l} \min L(\lambda) = \sum_{i_1, \dots, i_r \in J} \left[\sum_{j \in J} \ln \zeta_{i_1, \dots, i_r, j} (\lambda_{i_1, \dots, i_r} + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j}) \right. \\ \quad \left. + \lambda_{i_1, \dots, i_r} \right] + \sum_{i \in J} \pi_i \lambda_{-i} \quad \text{s.t.} \\ \lambda \in \Lambda_1(\nu, \pi^{(r)}), \end{array} \right.$$

where

$$\Lambda_1(\nu, \pi^{(r)}) = \begin{cases} \{\lambda \in \mathbb{R}^K / L(\lambda) < \infty\}, & \text{if } J \text{ is finite,} \\ \{\lambda \in \mathbb{R}_+^K / L(\lambda) < \infty, \sum_{k \in K} \lambda_k < \infty\}, & \text{if } J \text{ is infinite.} \end{cases}$$

According to Corollary 2.2 we have the next duality result.

Corollary 3.2. Assume that $\sum_{(i_1, \dots, i_r, j) \in I} \int_{\Omega_{i_1, \dots, i_r, j}} X_{i_1, \dots, i_r, j} d\nu_{i_1, \dots, i_r, j} < \infty$.

(i) **(weak duality)** If μ is a primal feasible solution of program (P3) and λ is a dual feasible solution of program (D3), then

$$-H(\mu; \nu) \leq L(\lambda).$$

Moreover, the equality holds if and only if

$$d\mu_{i_1, \dots, i_r, j} = \frac{e^{-[\lambda_{i_1, \dots, i_r} + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j}] X_{i_1, \dots, i_r, j}}}{\zeta_{i_1, \dots, i_r, j}(\lambda_{i_1, \dots, i_r} + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j})} d\nu_{i_1, \dots, i_r, j}, \quad \forall (i_1, \dots, i_r, j) \in I.$$

(ii) **(strong duality)** If $\lambda^* \in \text{Int } \Lambda_1(\nu, \pi^{(r)})$ is a dual optimal solution of program

(D3), then $\mu(\lambda^*) = \bigotimes_{(i_1, \dots, i_r, j) \in I} \mu_{i_1, \dots, i_r, j}(\lambda^*)$ given by

$$d\mu_{i_1, \dots, i_r, j}(\lambda^*) = \frac{e^{-[\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j}^*] X_{i_1, \dots, i_r, j}}}{\zeta_{i_1, \dots, i_r, j}(\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j}^*)} d\nu_{i_1, \dots, i_r, j}, \quad \forall (i_1, \dots, i_r, j) \in I$$

is a primal optimal solution of program (P3) and

$$-H(\mu(\lambda^*); \nu) = L(\lambda^*).$$

Remark 3.2. Taking $r = 1$, we obtain the maxentropic reconstruction of simple Markov chains with given common steady-state probabilities, with supplementary constraints of type (5) (see [13]) or without supplementary constraints (see [6]).

Example 3.1. Let $a \in \mathbb{R}_+$. For any $(i_1, \dots, i_r, j) \in I$, let

$$\Omega_{i_1, \dots, i_r, j} = \{0, a\}, \quad \nu_{i_1, \dots, i_r, j} = (1 - \theta_{i_1, \dots, i_r, j})\varepsilon_0 + \theta_{i_1, \dots, i_r, j}\varepsilon_a,$$

where $\theta_{i_1, \dots, i_r, j} \in [0, 1]$. Assume that

$$\sum_{(i_1, \dots, i_r, j) \in I} \theta_{i_1, \dots, i_r, j} < \infty.$$

We have

$$\zeta_{i_1, \dots, i_r, j}(y) = 1 - \theta_{i_1, \dots, i_r, j} + \theta_{i_1, \dots, i_r, j} e^{-y \cdot a}.$$

The dual problem (D3) has the following form:

$$\left| \begin{array}{l} \min L(\lambda) = \sum_{i_1, \dots, i_r \in J} \left\{ \sum_{j \in J} \ln [1 - \theta_{i_1, \dots, i_r, j} + \theta_{i_1, \dots, i_r, j} e^{-a(\lambda_{i_1, \dots, i_r} + \pi_{i_1, \dots, i_r}^{(r)} \lambda_{-j})}] \right. \\ \quad \left. + \lambda_{i_1, \dots, i_r} \right\} + \sum_{i \in J} \pi_i \lambda_{-i} \quad s.t. \\ \lambda \in \Lambda_1(\nu, \pi^{(r)}). \end{array} \right|$$

Let λ^* be an interior optimal solution of this problem. Then the primal problem

(P3) has the optimal solution $\mu(\lambda^*) = \bigotimes_{(i_1, \dots, i_r, j) \in I} \mu_{i_1, \dots, i_r, j}(\lambda^*)$ given by

$$\mu_{i_1, \dots, i_r, j}(\lambda^*) = \frac{(1 - \theta_{i_1, \dots, i_r, j})\varepsilon_0 + \theta_{i_1, \dots, i_r, j}e^{-a[\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)}\lambda_{-j}^*]}\varepsilon_a}{1 - \theta_{i_1, \dots, i_r, j} + \theta_{i_1, \dots, i_r, j}e^{-a[\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)}\lambda_{-j}^*]}},$$

$\forall (i_1, \dots, i_r, j) \in I$.

Hence the $r+1$ -dimensional matrix $P^{(r)} = \left(P_{i_1, \dots, i_r, j}^{(r)} \right)_{i_1, \dots, i_r, j \in J}$ given by

$$\begin{aligned} P_{i_1, \dots, i_r, j}^{(r)} &= E_{\mu_{i_1, \dots, i_r, j}(\lambda^*)}[X_{i_1, \dots, i_r, j}] \\ &= \frac{a\theta_{i_1, \dots, i_r, j}e^{-a[\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)}\lambda_{-j}^*]}}{1 - \theta_{i_1, \dots, i_r, j} + \theta_{i_1, \dots, i_r, j}e^{-a[\lambda_{i_1, \dots, i_r}^* + \pi_{i_1, \dots, i_r}^{(r)}\lambda_{-j}^*]}}, \quad \forall i_1, \dots, i_r, j \in J, \end{aligned}$$

is a r -step transition probability array of a homogeneous and stationary Markov chains of order r that verifies the imposed constraints (6), where

$$\pi^{(r)} = \left(\pi_{i_1, \dots, i_r}^{(r)} \right)_{i_1, \dots, i_r \in J}$$

is the given joint probability of the states at r consecutive times.

Remark 3.3. If the given joint probability $\pi^{(r)}$ is unknown, then it can be also reconstructed using the MEM method, from the imposed constraints (7), (8) and (9).

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University of Pitești,
Faculty of Mathematics and Informatics
E-mail: cbalcau@linux.math.upit.ro

University of București,
Faculty of Mathematics and Informatics;
E-mail: preda@fmi.unibuc.ro